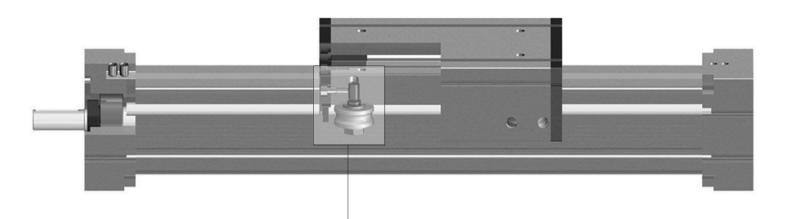
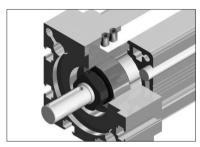
# Airtight Ball Screw Driving Linear Module

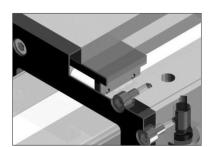




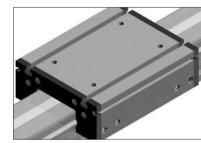


Possible to demonstrate system using various axis combination, and comfortable maintenance.
Long lifespan guaranteed by application of strong wearing-resistant aluminum material,

Convenient attachment with nut groove at side surface of rail and bearing supporter,



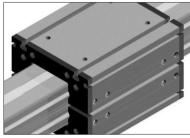
In order to prevent dust generation, belt is built—in and stainless steel cover is equipped.



MZ 40/60/80/100

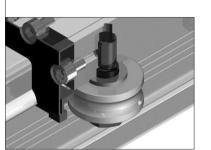
Basic slider block

- \* Possible for producing in any lengths for slider along with customer requirements
- \*Possible to select the number of roller bearings along with customer specification
- S : Standard slider
- T: Standard slider + Roller 2
- H: Standard slider + Roller 4

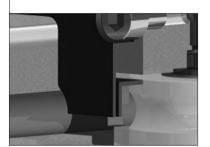


MZ 40/60/80/100-D

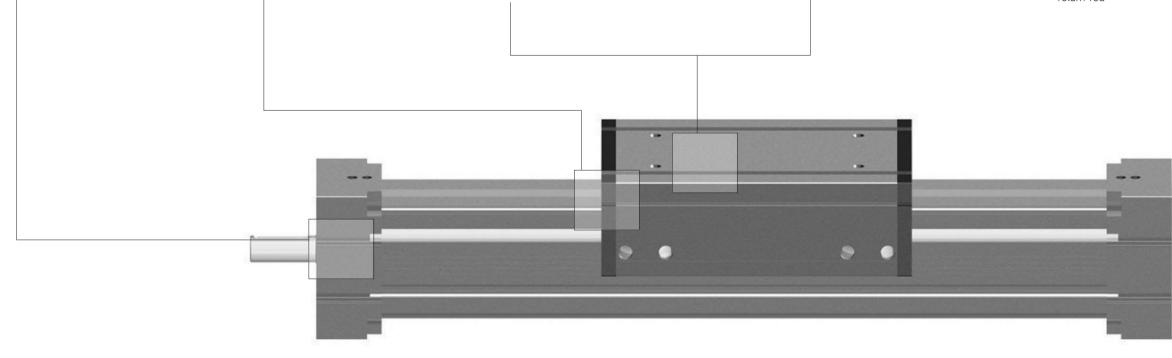
A structure which slider is mounted upper and lower side, suitable for heavy load rather than standard slider block and rail moving structure with fixing a slider.



Adopting high quality bearing steel shaft, sound driving guarantee during high speed conveyance. In application of chrome plated thermal treatment bearing steel for return rod of driving part, which super finishing is processed, it shows strong performance for wearing at contact part. In application of specially designed bolt combination, keeping set pressure between bearing and return rod

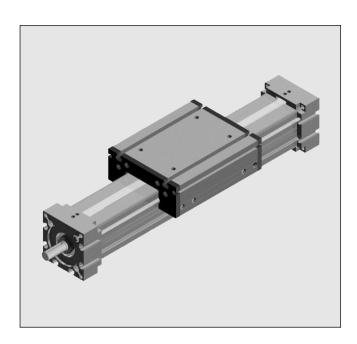


With mounting wool wiper on standard type, no hardening after long term utilization unlike rubber type wiper. Keeping constant frictional resistance of wiper by spring in sealing.



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# **Features**

- Combination of high speed linear guide and ball screw
- Combination of quality and economic performance
- Possible to select ball screw specification
- Various slider selection option
- Responding to various customer requirements such as mounting, accessory formation, etc.

# Order type



## TYPE

#### 2 Type number 40, 60, 80, 100

### 3 Slider type Non-symbol: Standard

D: Upper/Lower slider

## 4 Slider type

S: Standard slider T: Standard slider + Roller 2

H: Standard slider + Roller 4

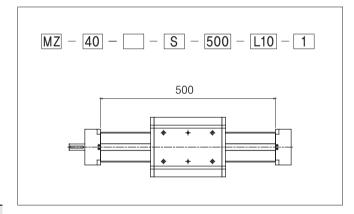
## 5 Rail length

### 6 Ball screw type

lı		Si	ze		
Type	Ball Screw	40	60	80	100
L5	16×5	0			
1.10	16×10	0			
L10	25×10		0	0	0
L25	25×25		0	0	0
L32	32×32				0

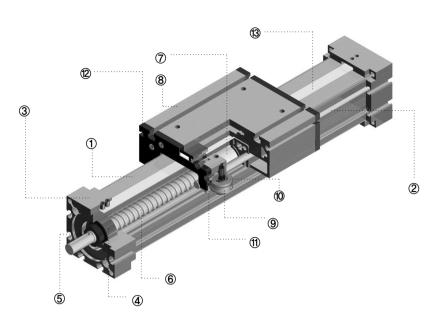
# 7 Quantity

# ► Ordering of Module



## Accessory

□ Motor (Name of company : (Model name : (Power :	) ) (kw>)	□ MSK (Sensor Bracket) □ Photo Sensor □ Proximity Sensor
☐ <b>Reducer</b> ☐ Pulley Reducer		☐ MBK (Mounting block) Quantity: EA
□Name of company : (Model name : (Model name :	) )	☐ Urethane stopper



# ► Specification of Components

No	Component name		Material	No	Component name	Material	
1	Rail		Aluminum alloy	8	Slider	Aluminum alloy	
	Product No.	Shaft					
	40	Ø6					
2	60	Ø10	Ball screw nut	Ball screw nut	9	Track roller	Bearing steel
	80	Ø12					
	100	Ø16					
3	Bearing housing		Aluminum alloy	10	Flat washer	_	
4	Bearing		-	11	Wiper	FELT	
5	Lock nut		_	12	Sealing	EP	
6	Ball screw		Cr-Mo steel	13	Steel cover	Stainless	
7	Ball screw nut		_				

## ▶ Performance sheet

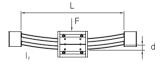
repeating accuracy	±0.025mm
Pitch accuracy	±0.05mm / 300mm
Straightness of rail	0.35mm/m
Parallelism between shafts	±0.02mm/m
Tolerance of length	±0.5mm
. D	

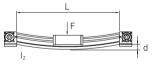
► Rail MAX, 3000mm

► Formula

Driving torque

# ▶ Max. deflection of rail





\*Formula for deflection of rail is the same to the whole dimension.

d = -	F X L <sup>3</sup>
u = -	192 × E × I

- E: Young's modulus, aluminum -70,000N/mm<sup>2</sup>
- d: deflection [mm]
  - F: load [N]
  - L: free length [mm]
  - I: 2' nd moment of area [mm4]

 $2000 \times \pi \times \varepsilon$ 

 $T_d \times n$ 

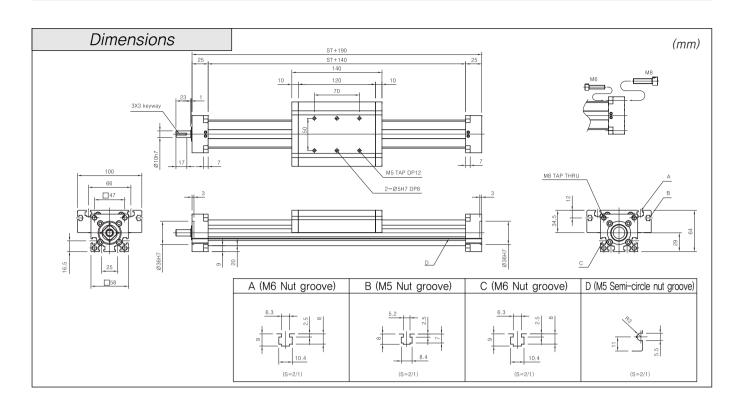
9550

 $F \times P \times S \times \mu$ 

- F: Applied load(N)
- P: Screw pitch(mm)
- S : Safety coefficient
- n: Screw rotation number per min. (min<sup>-1</sup>)
- μ: Frictional coefficient
- $\epsilon$ : Screw efficiency  $\sim 0.9$
- T<sub>d</sub>: Driving torque (Nm) Pm: Motor power (kw)

**Dimensions** 

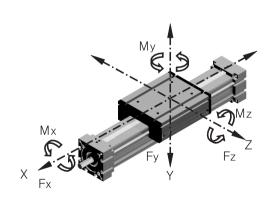
(mm)



# ► Technical data

• Standard ball-screw · · · · · · · · · · · · · · · · · · ·
No-load torque     1605 · · · · · · · · · 0.25Nm
1610 · · · · · · · · · · · · · · · · · · ·
• 2'nd moment of area $\cdot\cdot\cdot\cdot\cdot\cdot\cdot\cdot\cdot$ .
• Weights
Basic weight with zero stroke

# ▶ Forces and moments



	Forces/ Torques	Fx (N)	Fy (N)	Fz (N)	Mx (Nm)	My (Nm)	Mz (Nm)
14740	STATIC	1400	700	900	20	28	22
MZ40	DYNAMIC	1150	650	500	15	17	10

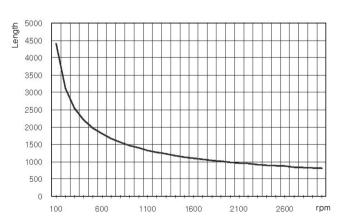
\* Having bigger value in case of selecting slider special specification (T.H)

# ▶ Ball screw allowable rotation number

$$N = \lambda \times \frac{D}{L} \times 10^{7}$$

N: allowable rotation number L: allowable rotation number D: Screw shaft sectional area λ: 15.1

# ▶ Ball screw allowable rotation number graph



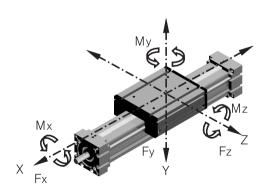
st If rotation speed increases, U ball screw may cause resonance owing to original frequency of screw axis, which causes disability of motion, so that it should be set to utilize under resonance point (risky speed).

# ► Technical data

• Standard ball-screw $\cdot$
No-load torque
2510 · · · · · · · · · · · · · · · · · · ·
2525 · · · · · · · · · · · · · · · · · ·
- 2'nd moment of area $\cdot\cdot\cdot\cdot\cdot\cdot\cdot\cdot\cdot\cdot$
• Weights
Basic weight with zero stroke · · · · · · · · · 5.8kg
Weight/100mm stroke · · · · · · · · · · · · · · 0.86kg

A (M8 Nut groove)

## ▶ Forces and moments



Slider Type	Forces/ Torques	Fx (N)	Fy (N)	Fz (N)	Mx (Nm)	My (Nm)	Mz (Nm)
14700	STATIC	2400	1500	2700	57	120	86
MZ60	DYNAMIC	1800	990	1800	33	95	66

<sup>\*</sup> Having bigger value in case of selecting slider special specification (T.H)

# ▶ Ball screw allowable rotation number

C (M6 Nut groove) D (M5 Semi-circle nut groove)

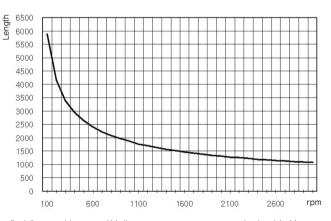


N: allowable rotation number L: allowable rotation number D: Screw shaft sectional area

λ: 15.1

B (M5 Nut groove)

# ▶ Ball screw allowable rotation number graph

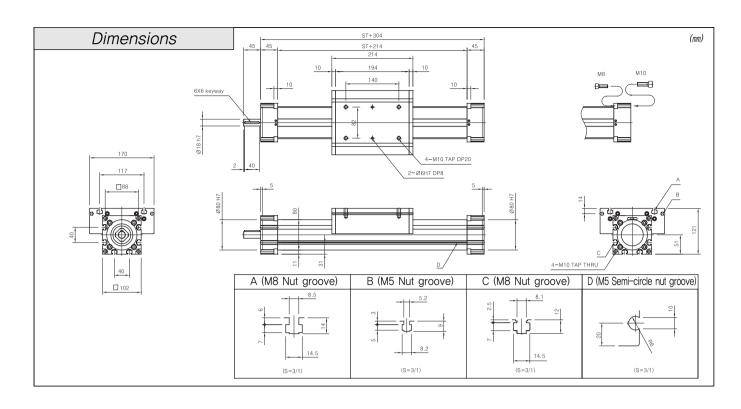


st If rotation speed increases, U ball screw may cause resonance owing to original frequency of screw axis, which causes disability of motion, so that it should be set to utilize under resonance point (risky speed).

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**Dimensions** 

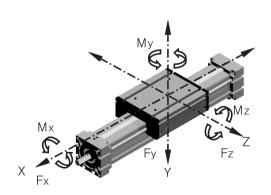
D (M5 Semi-circle nut groove)



# ► Technical data

• Standard ball-screw · · · · · · · · · · · · · 25× 25×	
No-load torque	
2510 0.6N	
2525 · · · · · · · · · · · · · · · · · ·	١m
- 2'nd moment of area $\cdot\cdot\cdot\cdot\cdot\cdot\cdot\cdot$	
Weights	
Basic weight with zero stroke · · · · · · · · · · 11kg	
Weight/100mm stroke · · · · · · · · · · · · · · · 1.7k	J

## ▶ Forces and moments



Slider Type	Forces/ Torques	Fx (N)	Fy (N)	Fz (N)	Mx (Nm)	My (Nm)	Mz (Nm)
14700	STATIC	2400	1500	2700	80	140	100
MZ80	DYNAMIC	1800	990	1800	50	110	75

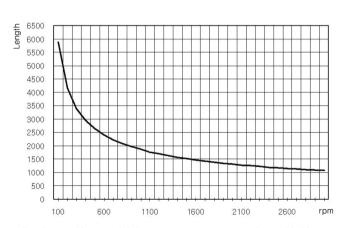
\* Having bigger value in case of selecting slider special specification (T.H)

# ▶ Ball screw allowable rotation number

$$N = \lambda \times \frac{D}{L} \times 10^7$$

N: allowable rotation number
L: allowable rotation number
D: Screw shaft sectional area
λ: 15,1

# ▶ Ball screw allowable rotation number graph

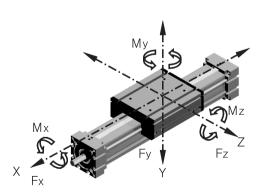


 If rotation speed increases, U ball screw may cause resonance owing to original frequency of screw axis, which causes disability of motion, so that it should be set to utilize under resonance point (risky speed),

# ► Technical data

• Standard ball-screw • • • • • • • • • • • • • • • 25×10 25×25 32×32
• No-load torque 2510 · · · · · · · · · · · · · · · · · · 0,6Nm 2525 · · · · · · · · · · · · · · · · 0,8Nm 3232 · · · · · · · · · · · · · · · 0,9Nm
- 2'nd moment of area · · · · · · · · $I_{\nu}$ =58.4×10 <sup>5</sup> mm <sup>4</sup> $I_{z}$ =61.9×10 <sup>5</sup> mm <sup>4</sup>
Weights  Basic weight with zero stroke

## ▶ Forces and moments



	Slider	Forces/	Fx	Fy	Fz	Mx	Му	Mz
	Type	Torques	(N)	(N)	(N)	(Nm)	(Nm)	(Nm)
	MZ100	STATIC	9000	3300	7200	280	690	380
		DYNAMIC	7500	2000	5800	200	470	250

<sup>\*</sup> Having bigger value in case of selecting slider special specification (T.H)

# ▶ Ball screw allowable rotation number

C (M6 Nut groove)

$$N = \lambda \times \frac{D}{L} \times 10^{7}$$

N: allowable rotation numberL: allowable rotation numberD: Screw shaft sectional area

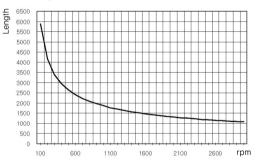
B (M5 Nut groove)

λ: 15,1

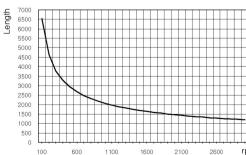
A (M8 Nut groove)

# ▶ Ball screw allowable rotation number graph

### • 25×10/25×25



### • 32×32



\* If rotation speed increases, U ball screw may cause resonance owing to original frequency of screw axis, which causes disability of motion, so that it should be set to utilize under resonance point (risky speed),

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